What I did this week:

This week we printed and assembled a board from the LID router, it’s been having issues with shorting across the copper left on the board.

Obstacles?:

We have been spending far too much time working on getting the copper to cease shorting, so I’m just going to go at it with a knife.

What I plan to do next week:

Start prototyping this thing with an arduino. We will do a simple step program treating the motor like a stepper after we finish mapping all the motor’s states